

EMOTE LASER BEAM DELIVERY SYSTEM AND
METHOD FOR USE WITH A ROBOTIC
POSITIONING SYSTEM FOR ULTRASONIC
TESTING PURPOSES

Inventor: Tommy E. Drake, Jr. 019843.0241
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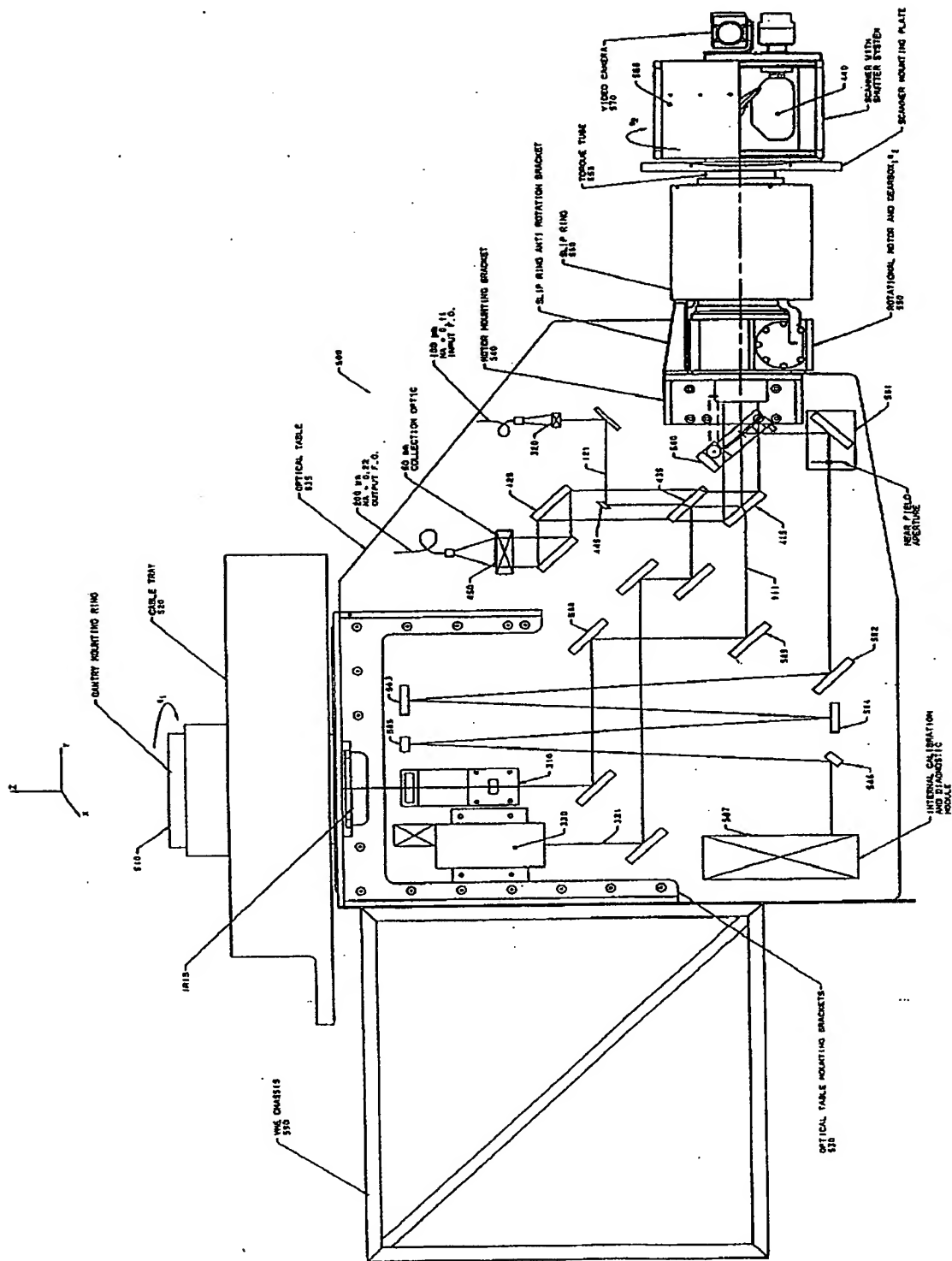
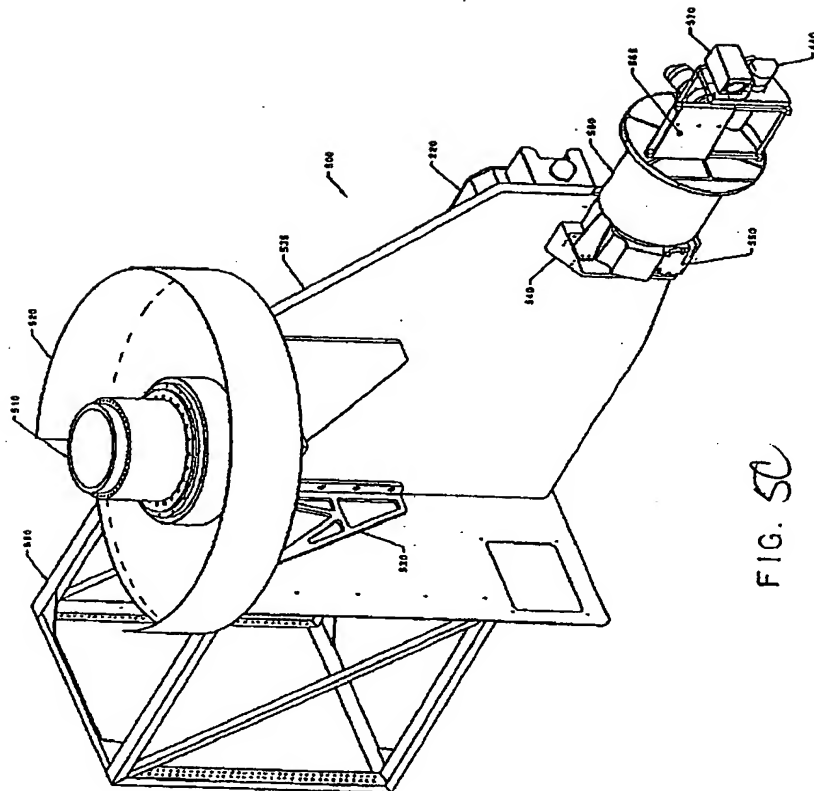
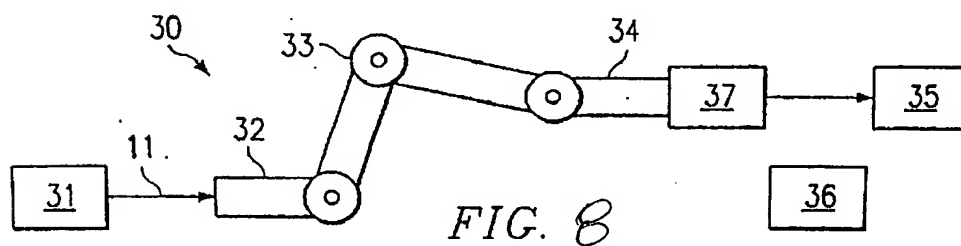
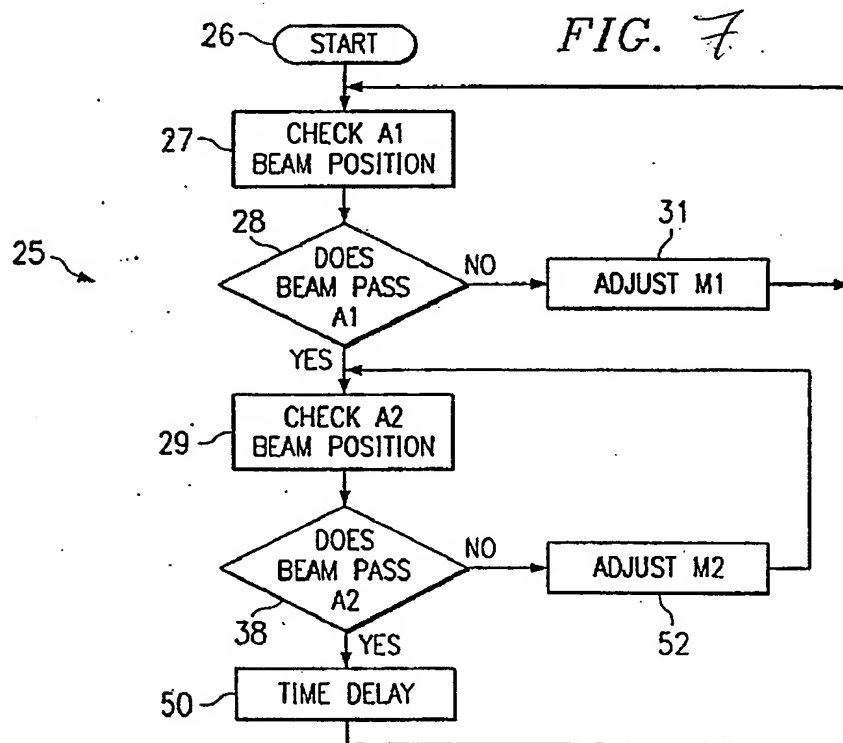
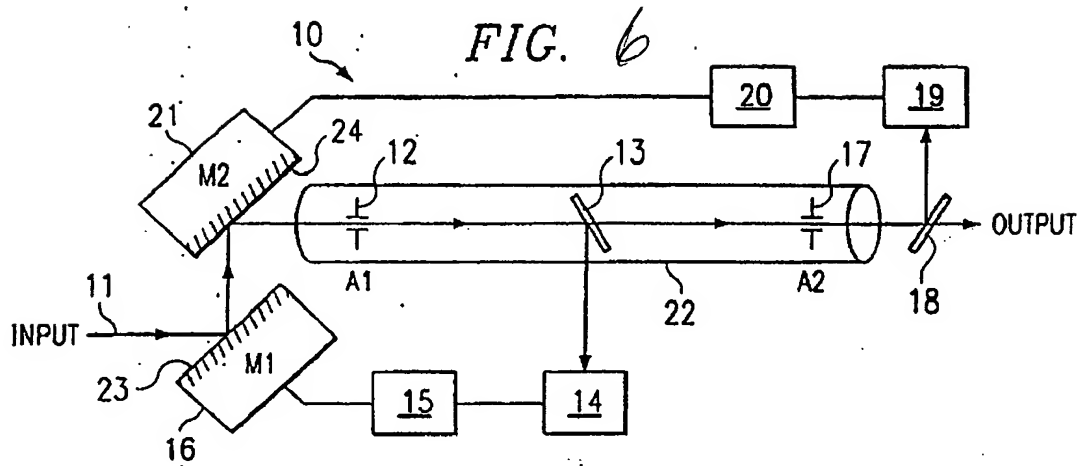


FIG. SB

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FIG. 9A

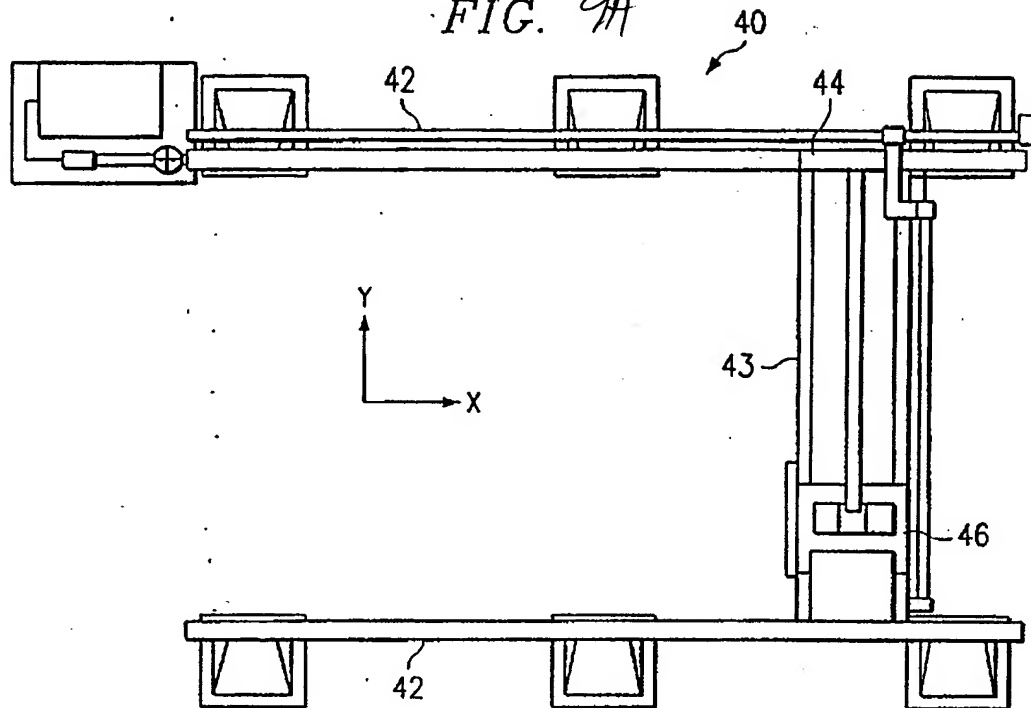
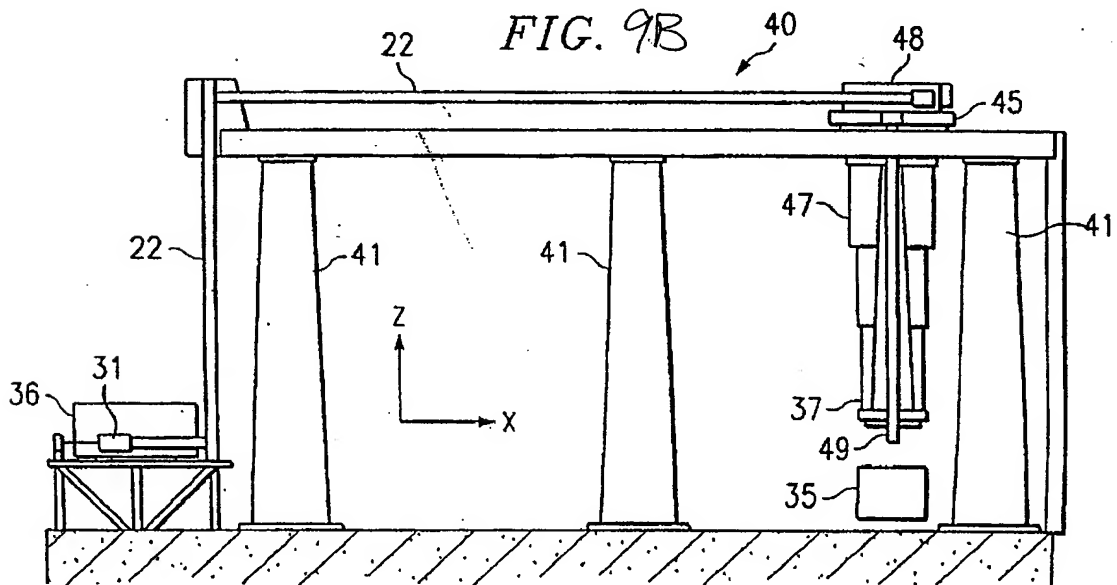


FIG. 9B



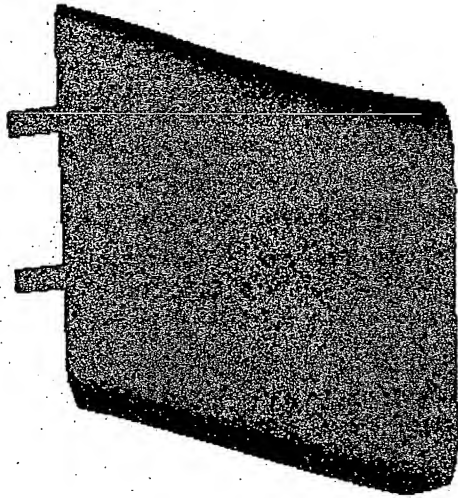


FIG. 10C

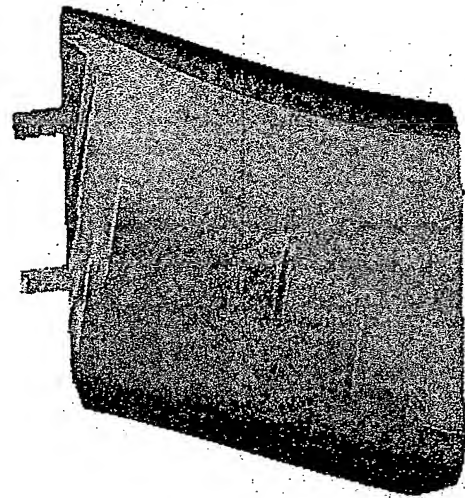


FIG. 10F

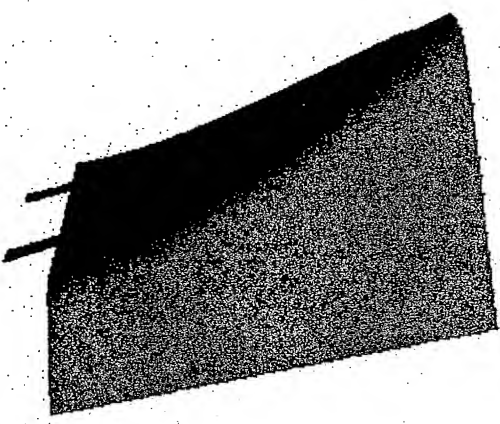


FIG. 10B

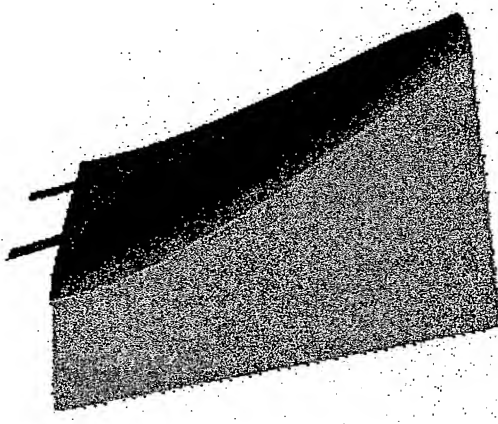


FIG. 10E

Angle = 30 degrees

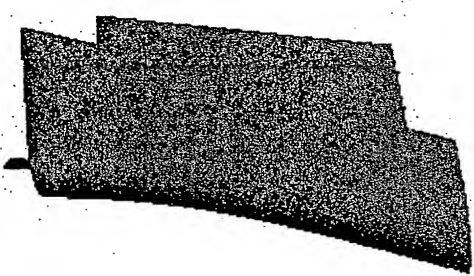


FIG. 10A

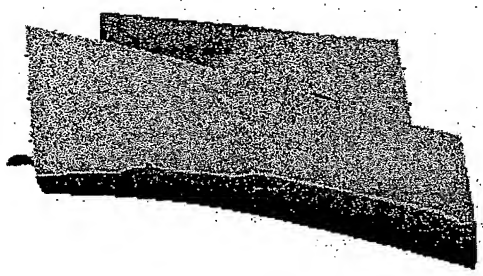


FIG. 10D

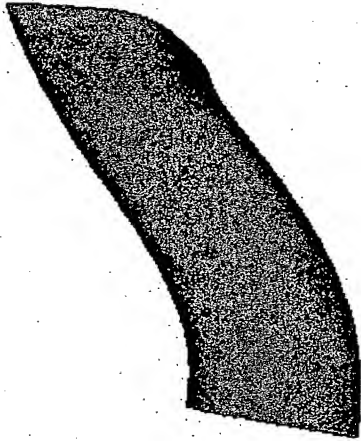


FIG. 11C

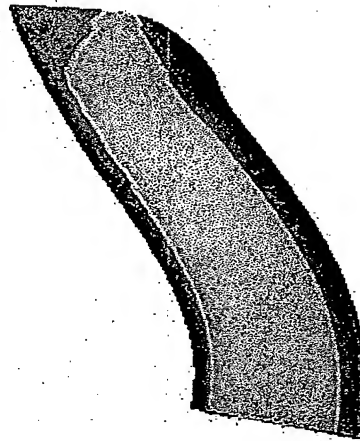


FIG. 11F

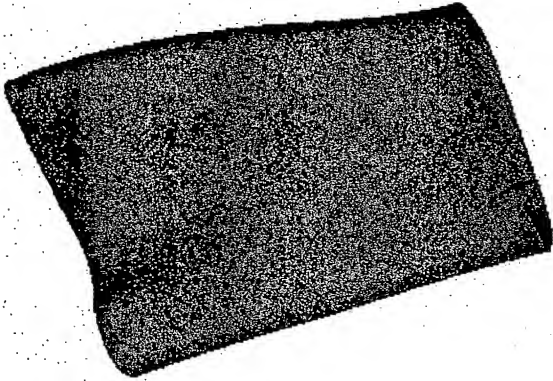


FIG. 11B

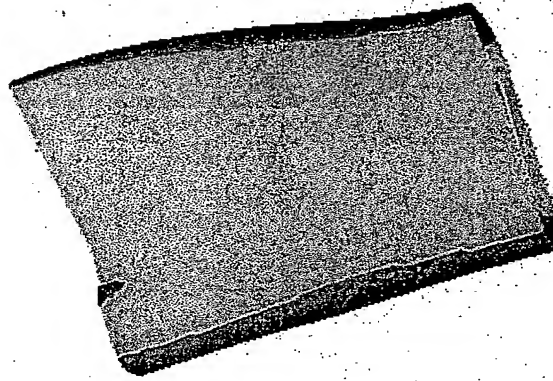


FIG. 11E

Angle = 30 degrees

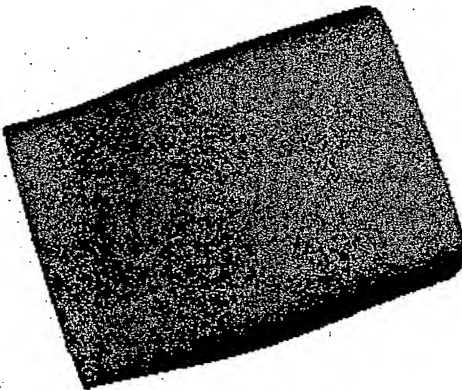


FIG. 11A

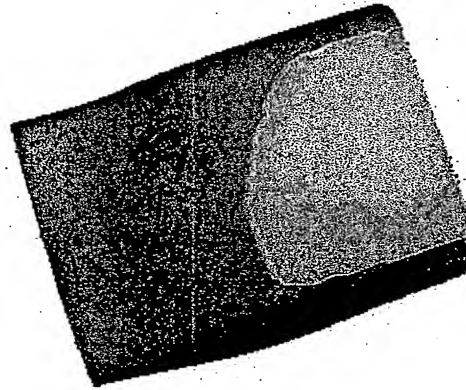


FIG. 11D

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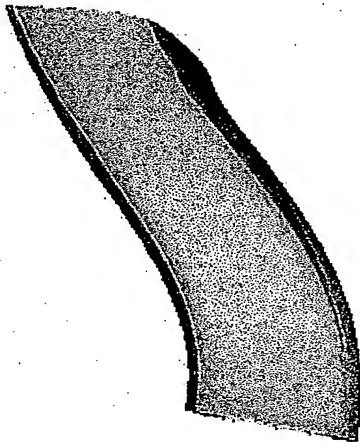


FIG. 12C



FIG. 12F

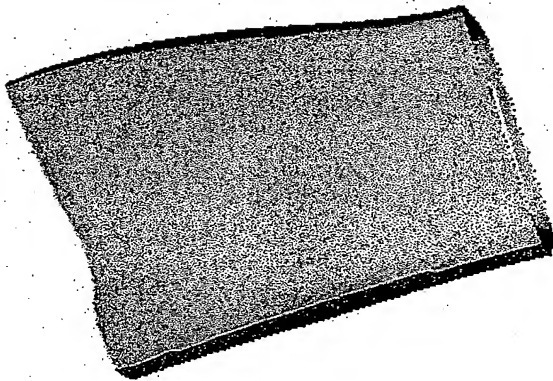


FIG. 12B
Angle = 45 degrees

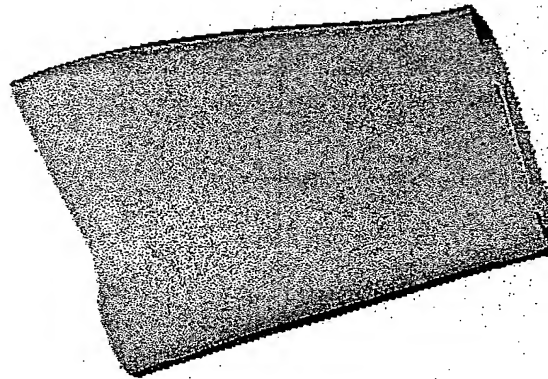


FIG. 12E
Angle = 60 degrees

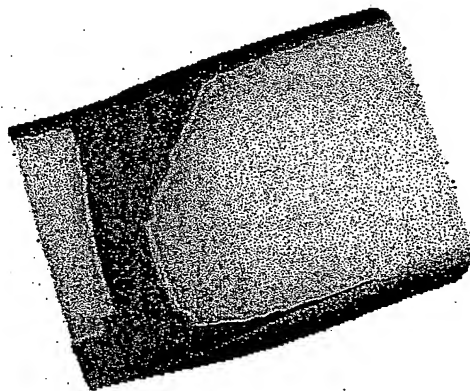


FIG. 12A

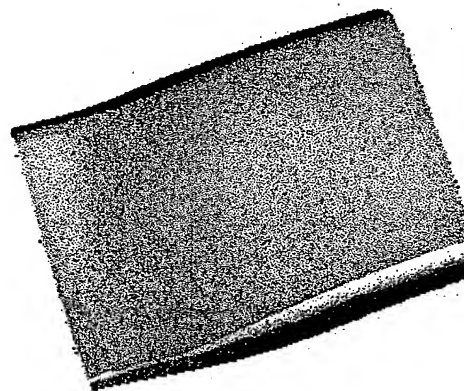


FIG. 12D

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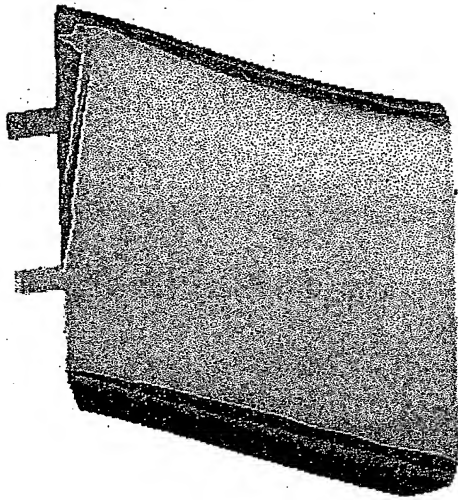


FIG. 13C

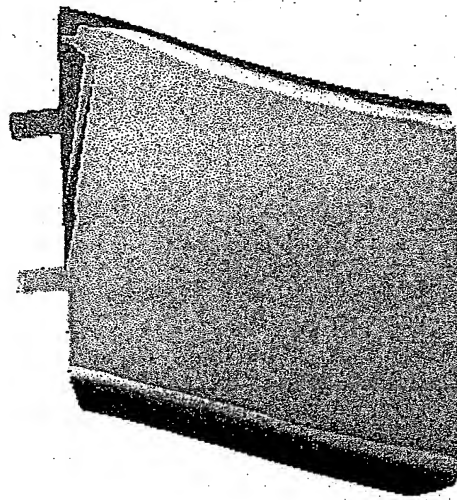


FIG. 13F

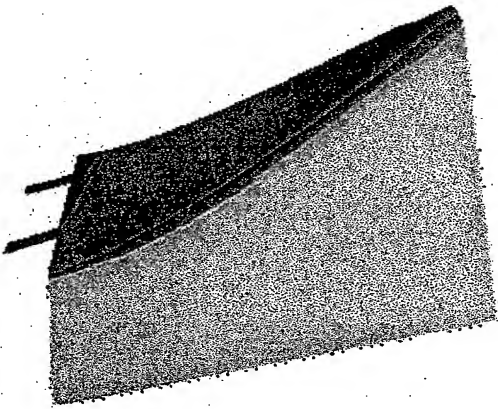


FIG. 13B

Angle = 45 degrees

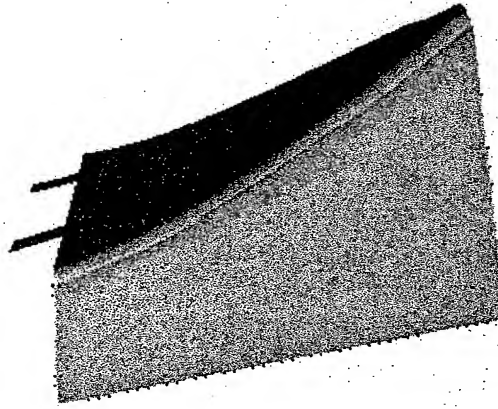


FIG. 13E

Angle = 60 degrees

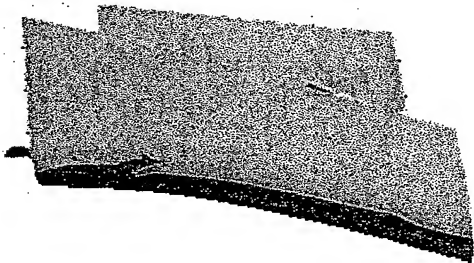


FIG. 13A

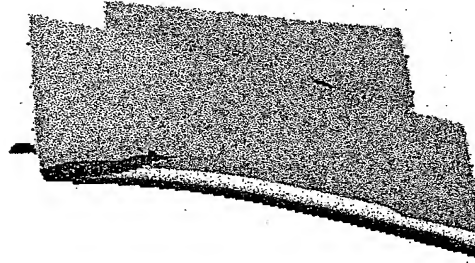


FIG. 13D

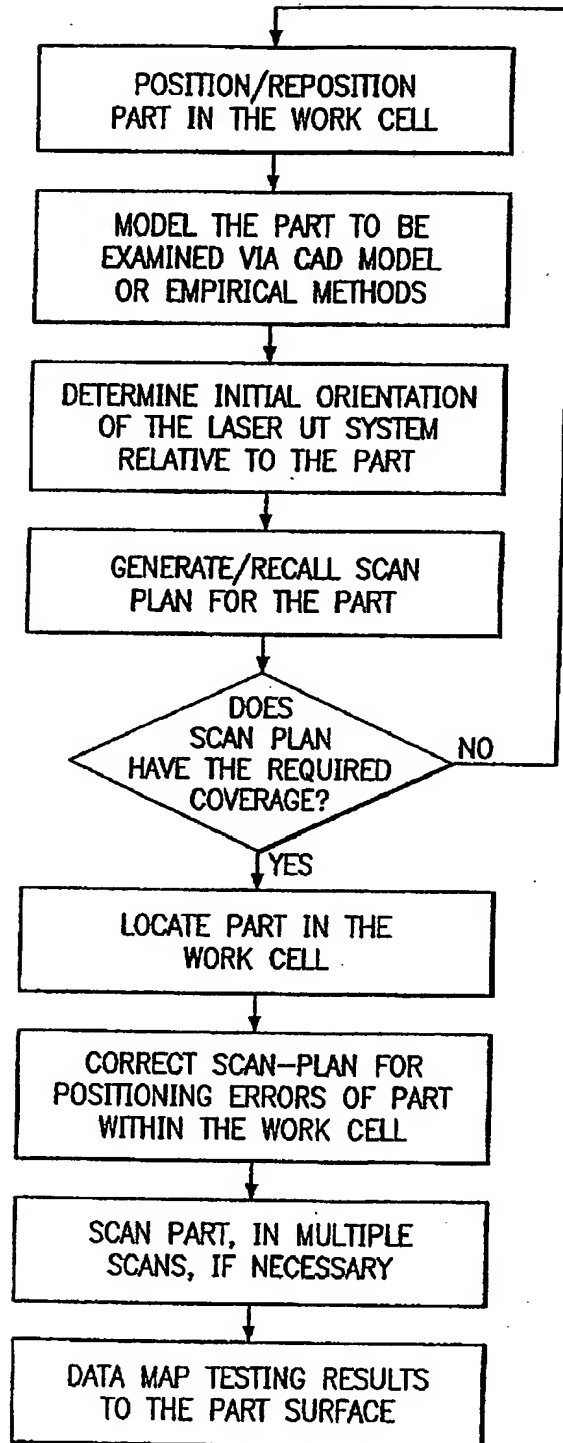
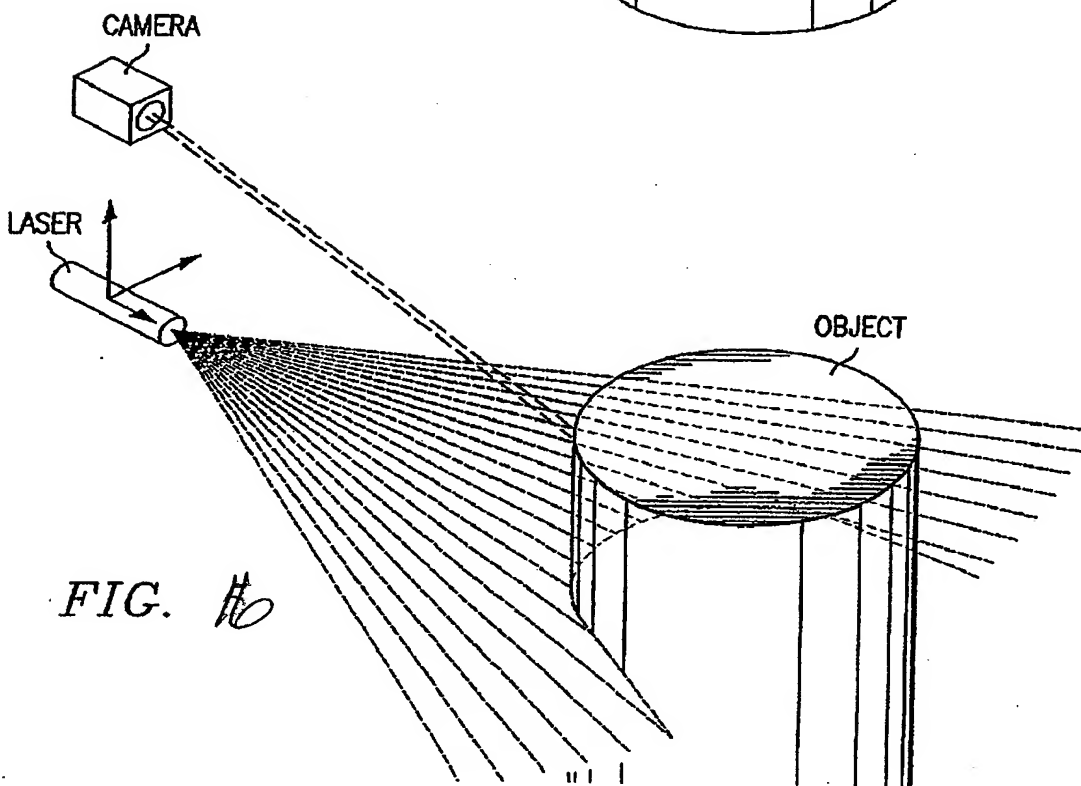
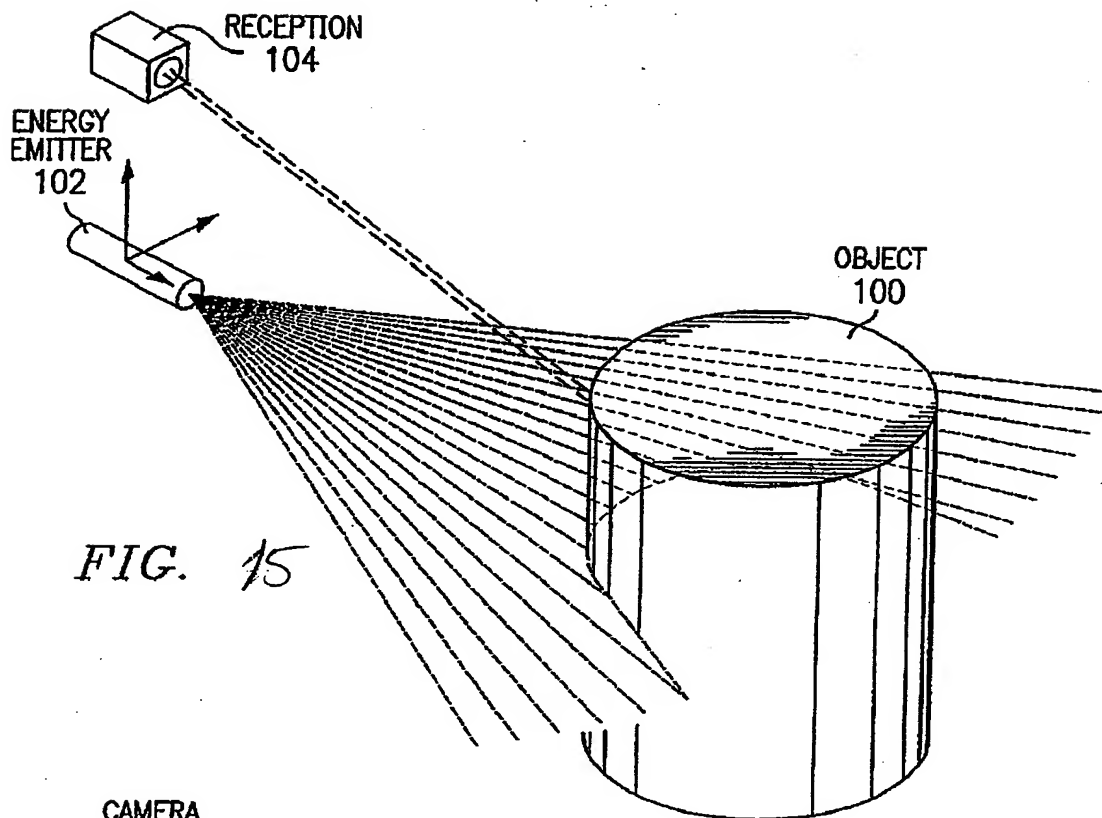


FIG 14

EMOTE LASER BEAM DELIVERY SYSTEM AND
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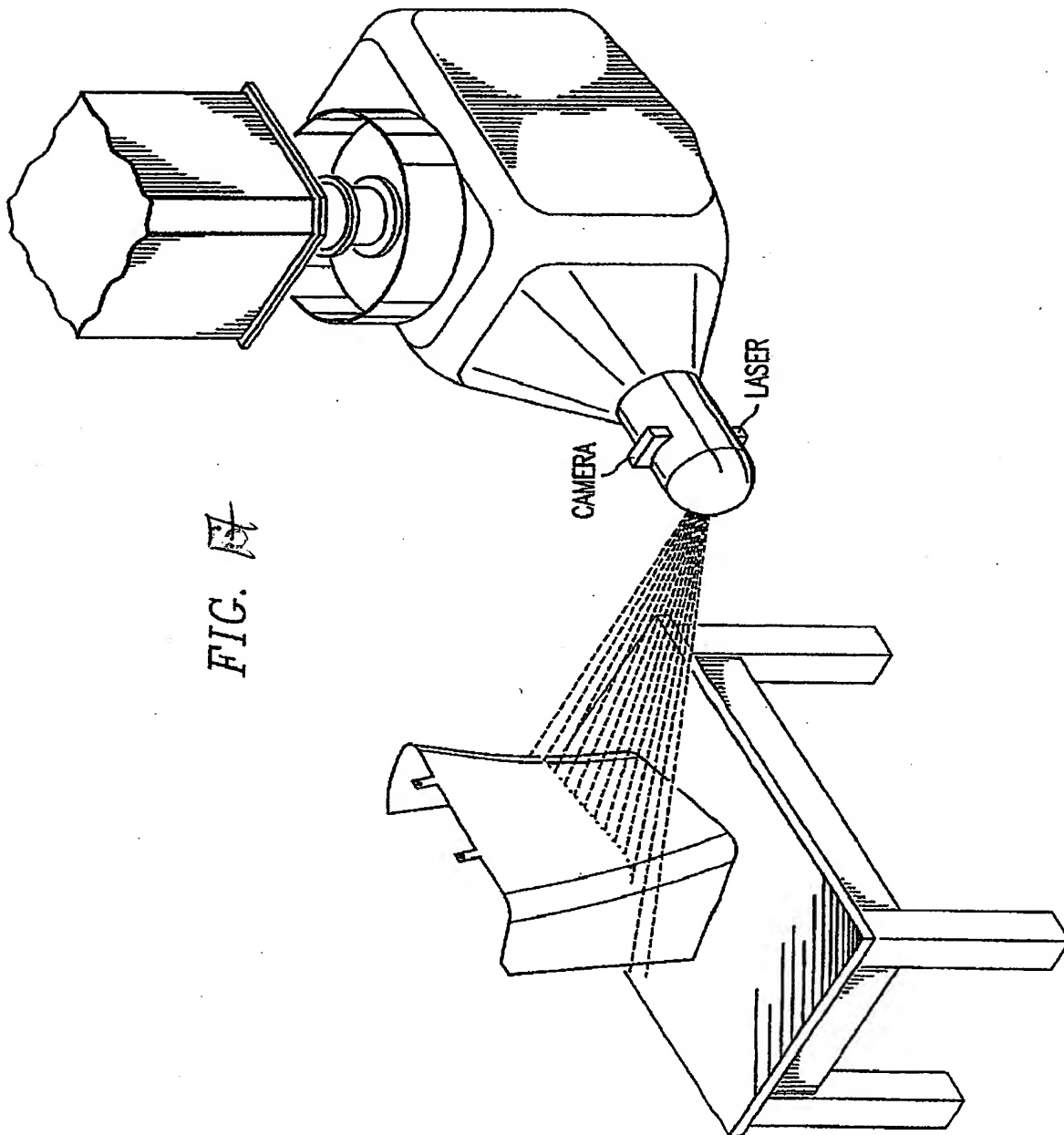
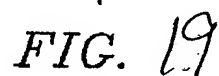
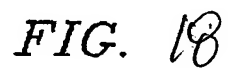


FIG. 17



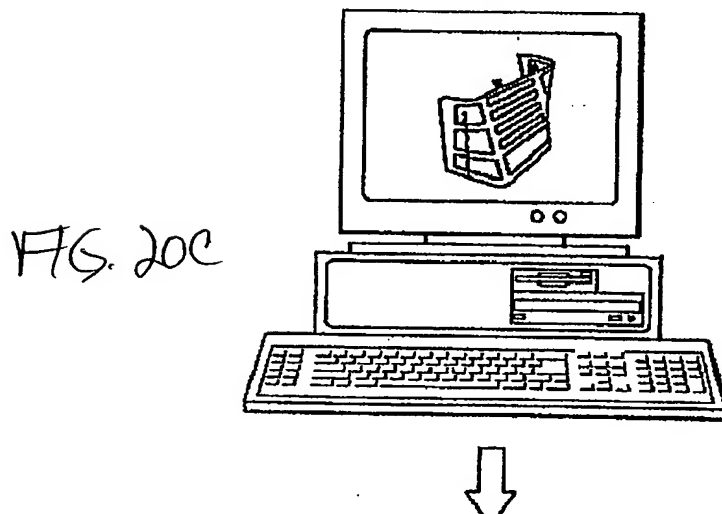
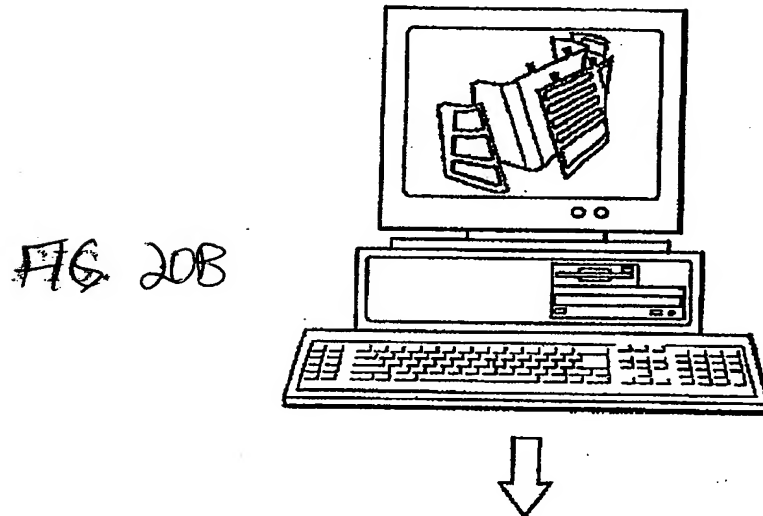
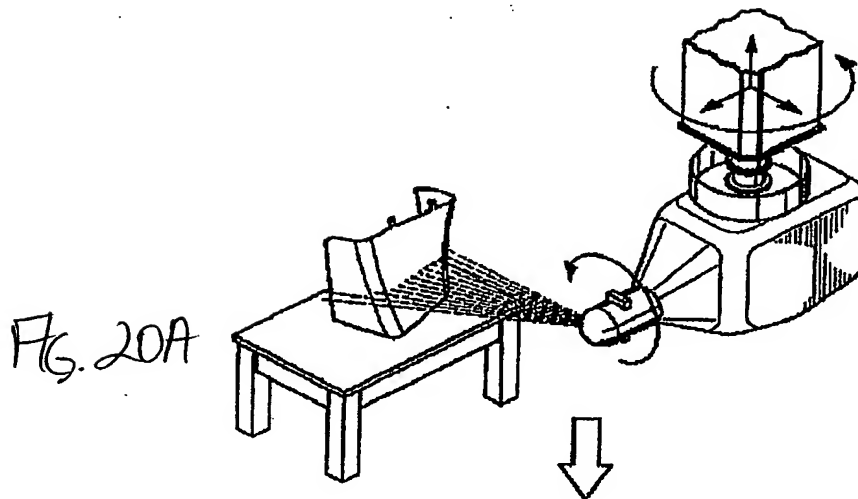


FIG. 20D

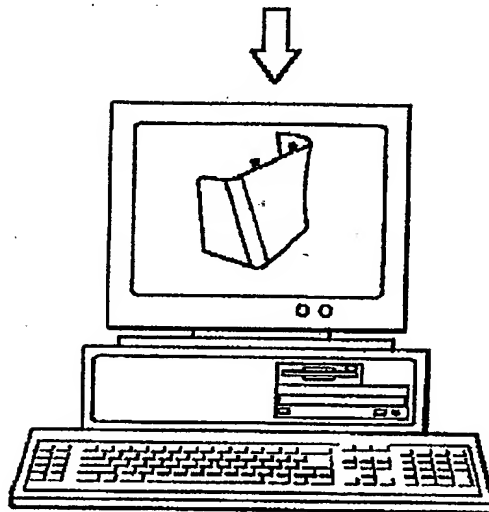


FIG. 20E

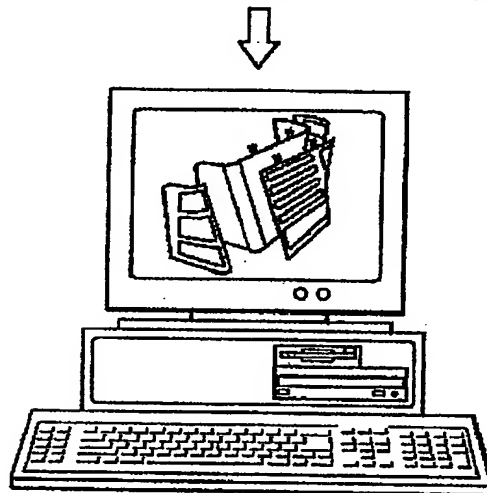


FIG. 20F

